



NIC-FPS Preliminary Design Review

Instrument Control and Software *Stéphane Béland*

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CASA-ARL

Boulder, CO





NIC-FPS Preliminary Design Review

Overview

- **Requirements**
- **Block Diagram**
- **Motor Control**
- **Temperature and Pressure**
- **Remote Communication**
- **Instrument Control Software**
- **Data Reduction**
- **Observing Procedures**





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Requirements

■ Remote motor control

- ▶ 4 to 8 moving mechanisms (cryogenic and ambient temperature)
- ▶ 2 or 4 switches per mechanism (micro or magnetic switches)

■ Remote temperature and pressure monitoring

- ▶ Monitor several locations inside dewar (60-300K)
- ▶ Monitor dewar pressure (10^{-3} to 10^{-6} Torr)

■ Remote communication

- ▶ Standard protocol (Ethernet, RS232)

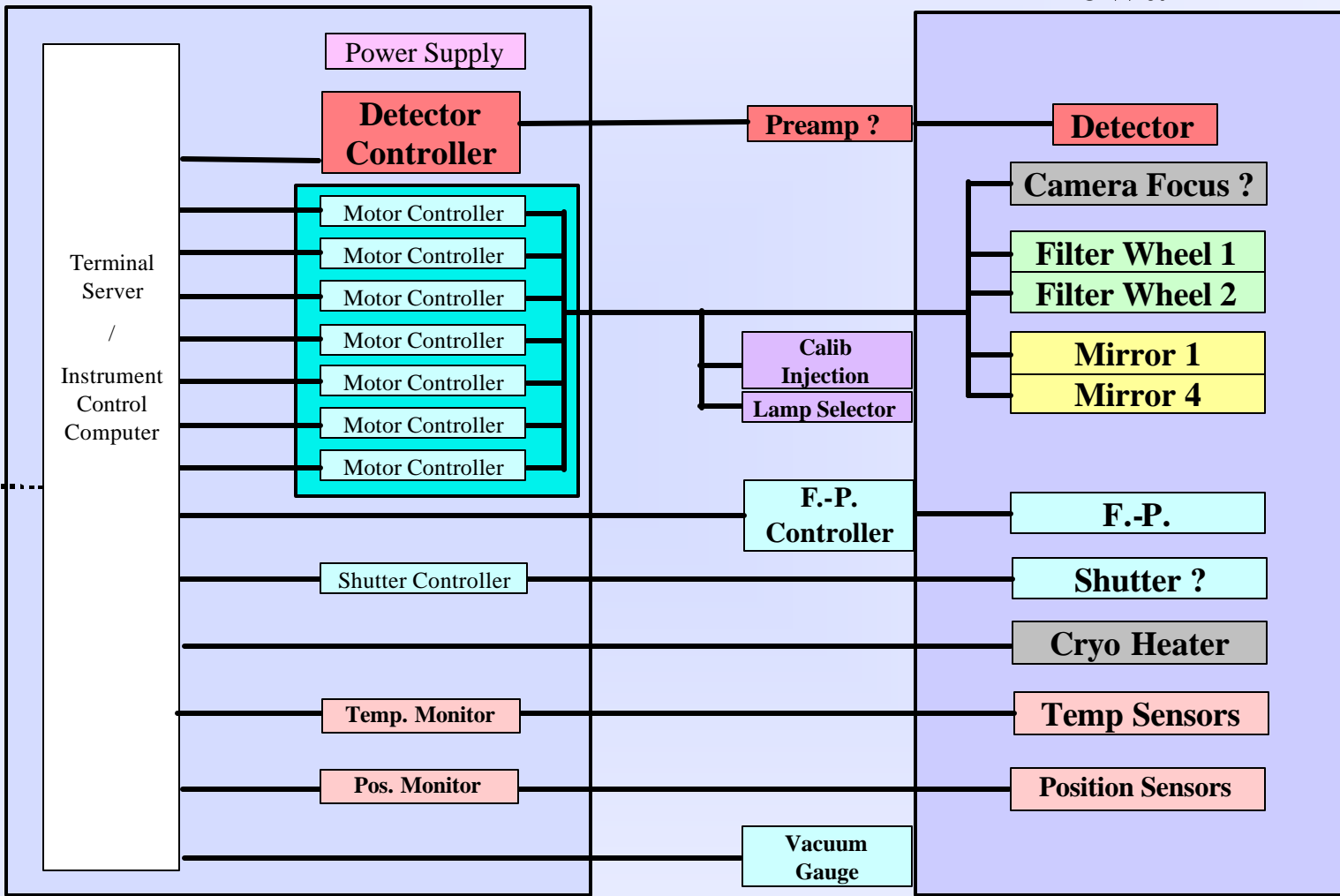
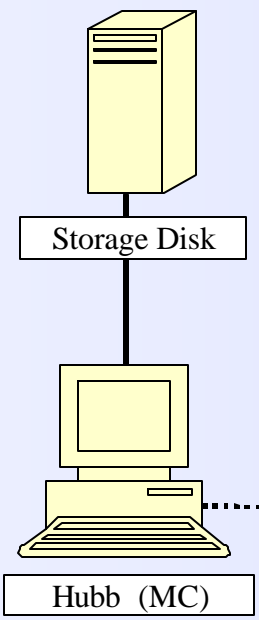




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Electronics Crate

Dewar





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Remote Motor Control

- Serial RS232 motor controllers (API DM 224i)
- Cryogenic stepper motors (API ST 0171)

Remote Temperature and Pressure

- Serial RS232 temperature monitor (Lakeshore 218)
- Serial RS232 pressure monitor (Varian eyeSYS mini-BA)

Remote Communication

- Ethernet from Master Controller (MC) to Instrument Control Server (ICS) (Lantronix ETS16P)
- RS232 from Instrument Control Server (ICS) to instrument devices
- Instrument Control Computer (ICC) accesses each device through a specific port of the ICS





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Instrument Control Software

- Provide user-friendly control of all aspects of the instrument
 - filter wheels, optical path, shutter control, camera focus, calibration lamps/mirrors
 - Fabry-Pérot spacing
- Maintain and inform user of status of instrument
- Software under version management
- Documentation will be provided
- **Adhere to ARC standards (using new Python Instrument Control Interface & scripts)**
- Observing scripts: F-P scanning, Co-adding images, Multiple Sampling Readout (to beat down read noise), Exposure Time Calculator, ...





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Data Reduction Software (Imaging Mode)

- Detector (non-destructive) read out: Reset, Reference Frame, Integration, Raw Frame
- Co-add N frames: in controller or computer memory or post processing with referencing
- Flat field for each filter position (internal, “dome”, or sky)
- Bad pixel map
- Cosmic ray cleaning
- Geometric distortion map
- IRAF or IDL or ??
- Assuming average 10sec exposure and 50% duty cycle over 10 hours (2MB per image)
 - 3.6GB per night of unprocessed data

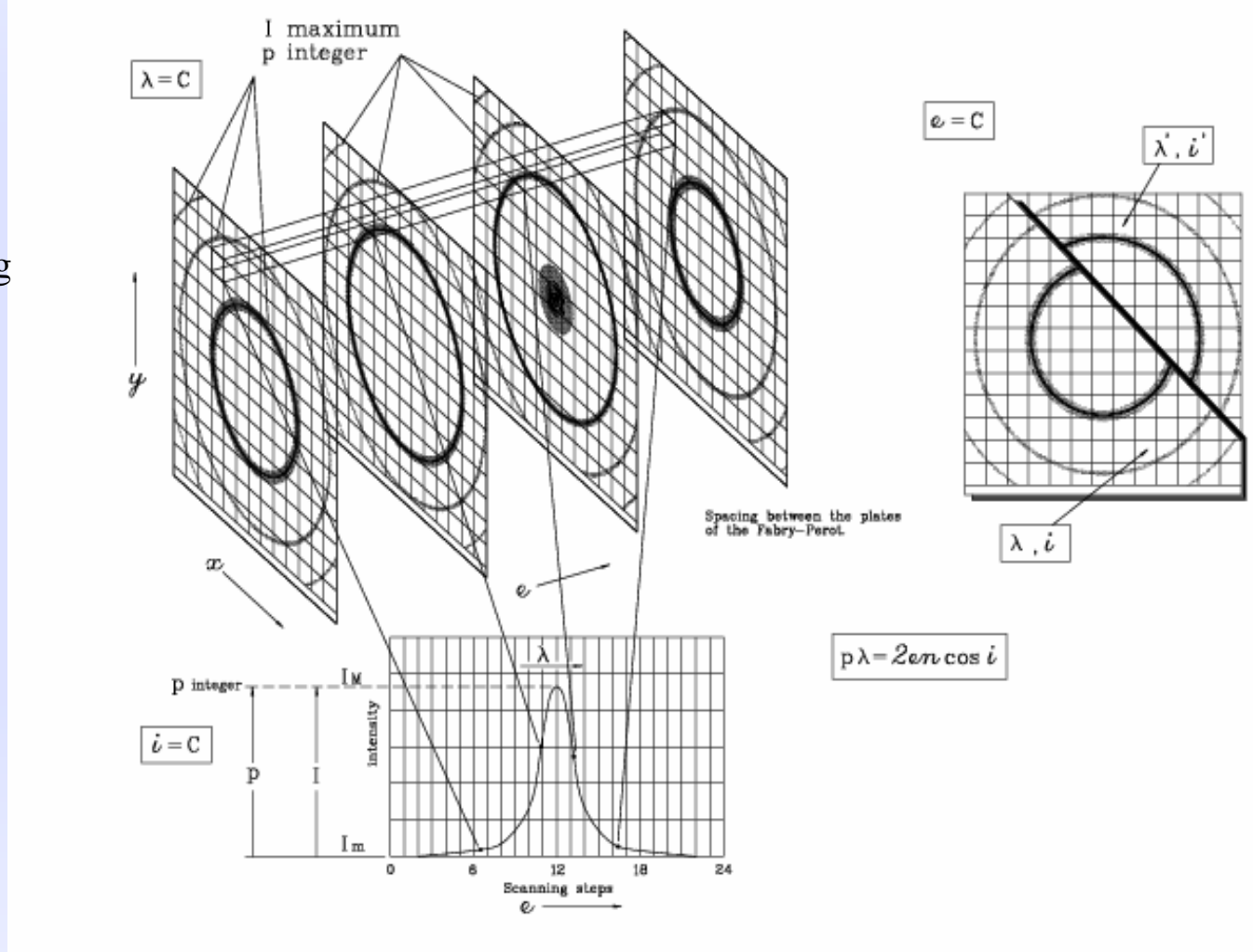




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Data Reduction Software (Fabry-Perot Spectroscopic Mode)

- Standard image processing
- Generate phase map
- Extract spectrum:
 - any region, any sampling
- Standard spectro. reduction
 - wavelength calibration
 - photometric calibration
- IRAF or IDL or ??
 - IRAF routines available





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Observing Procedures

- Imaging Mode:
 - Adjust focus (filter change, mode change)
 - Take flat fields for every filter to be used during observations
- Fabry-Perot Spectroscopic Mode:
 - Adjust focus (filter change, mode change)
 - Adjust/verify etalon's parallelism at setup
 - Measure etalon's finesse at setup (maybe)
 - Measure etalon's scanning constant (Wavelength / Binary Coded Values)
 - Perform wavelength calibration (lamps or OH lines) at spacing to be used during observations
 - Take flat fields at every combination of spacing and filter to be used during observations (White Light Cube)
 - Calibration Stars

